



# Computer Methods (MAE 3403)

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## Numerical differentiation and integration



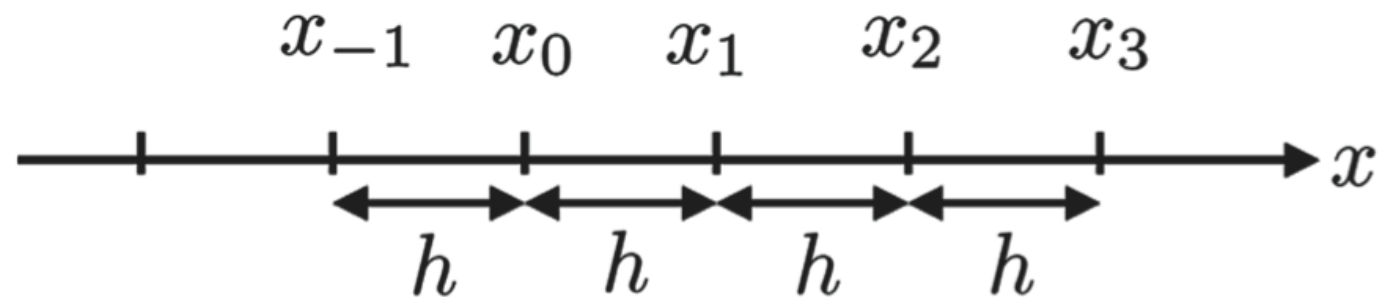
# Motivation

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- Many systems change over time, space and other dimensions of interest. Such changes are modelled as function derivatives.
- In practice, the function may not be known or the function may be implicitly known by data points.
- Can we compute derivatives numerically rather than analytically?

# Numerical differentiation

- Compute  $df(x)/dx$  numerically
- Numerical grids: `linspace` in 1-D

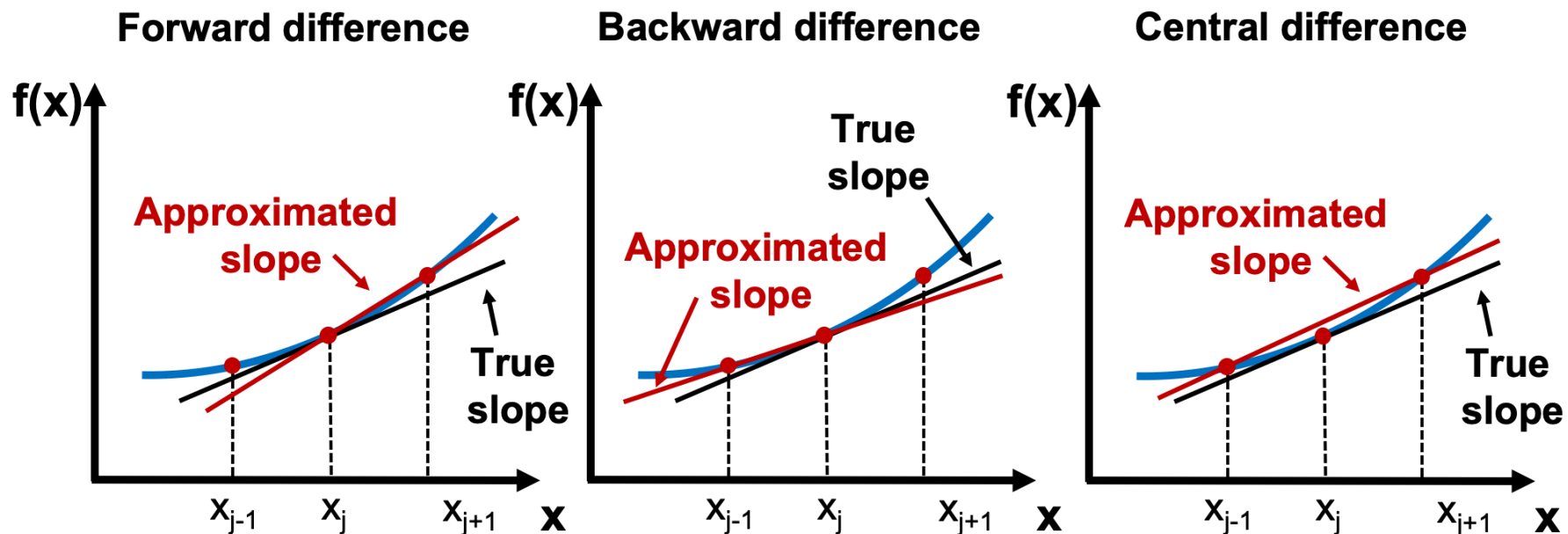


- Although a function may be continuous, its discretized version is more useful for differentiation and integration.

# Finite difference approximating derivatives

$$f'(a) = \lim_{x \rightarrow a} \frac{f(x) - f(a)}{x - a}$$

- We use values in the neighborhood of  $a$  to approximate the derivative





# Three types of differences as derivative

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- Forward difference

$$f'(x_j) \approx \frac{f(x_{j+1}) - f(x_j)}{x_{j+1} - x_j}$$

- Backward difference

$$f'(x_j) \approx \frac{f(x_j) - f(x_{j-1})}{x_j - x_{j-1}}$$

- Central difference (better accuracy)

$$f'(x_j) \approx \frac{f(x_{j+1}) - f(x_{j-1})}{x_{j+1} - x_{j-1}}$$



# Python

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- Finite difference computation: `d=np.diff(f)`
  - $d(i) = f(i+1) - f(i)$
- The size of the output is one less than the size of the input

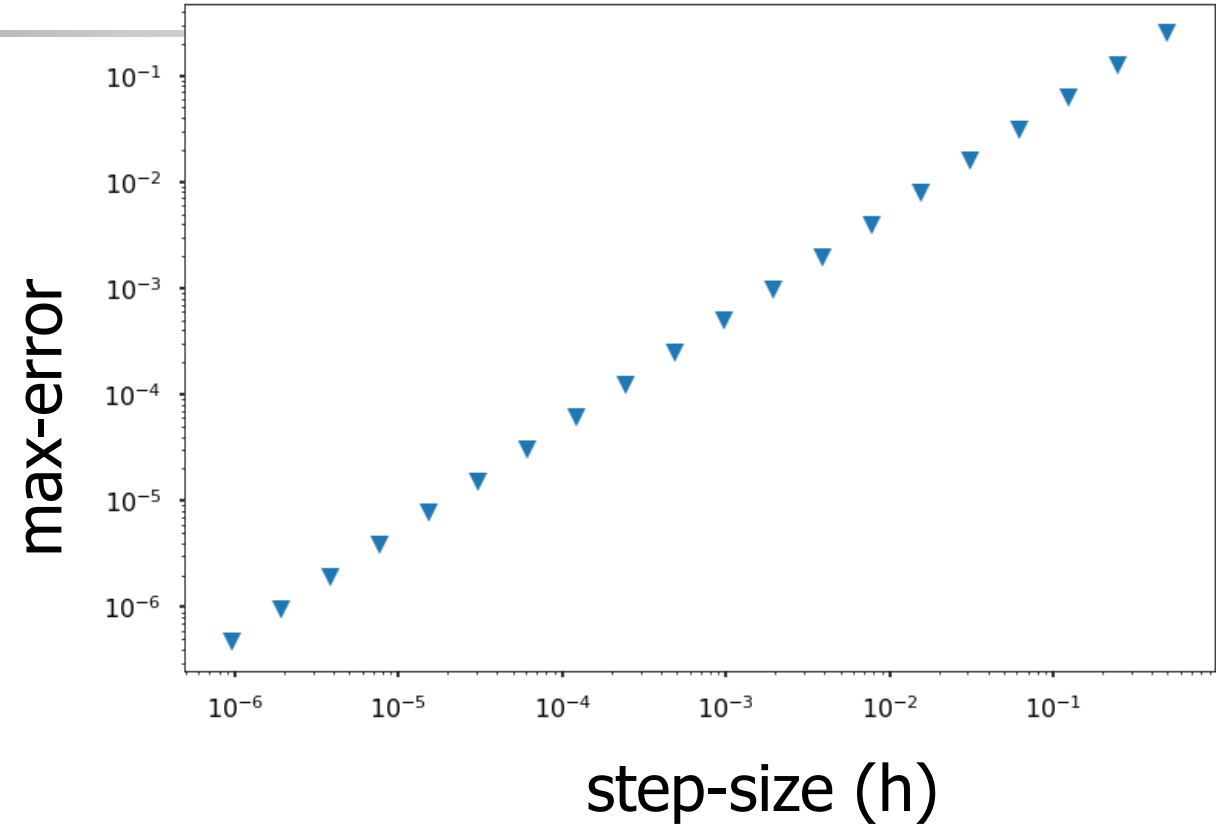
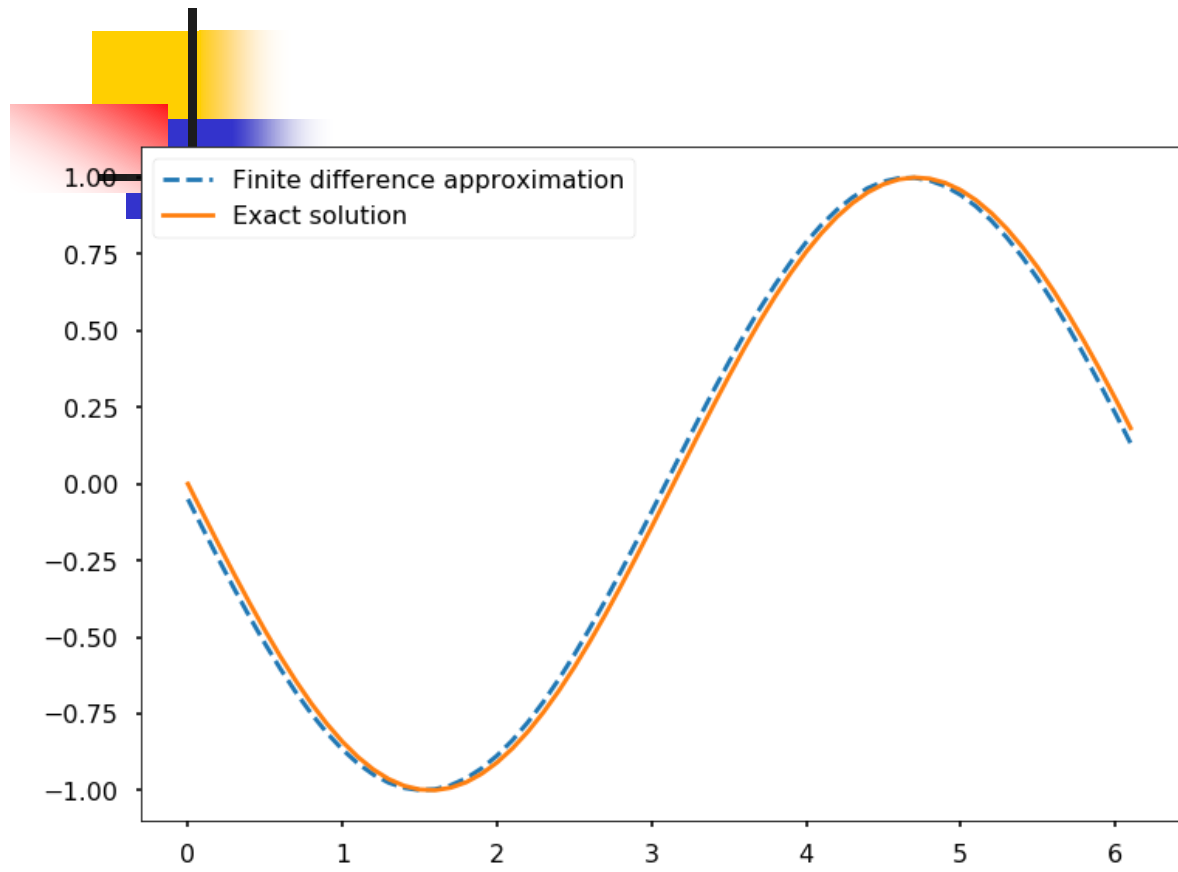


# Example

```
import numpy as np
import matplotlib.pyplot as plt

# step size
h = 0.1
# define grid
x = np.arange(0, 2*np.pi, h)
# compute function
y = np.cos(x)
# compute vector of forward differences
forward_diff = np.diff(y)/h
# compute corresponding grid
x_diff = x[:-1:]
```

```
# compute exact solution
exact_solution = -np.sin(x_diff)
# Plot solution
plt.figure(figsize = (12, 8))
plt.plot(x_diff, forward_diff, '--', \ label =
'Finite difference approximation')
plt.plot(x_diff, exact_solution, \ label =
'Exact solution')
plt.legend()
plt.show()
# compute max error
max_error = max(abs(exact_solution -
forward_diff))
print(max_error)
```







# Higher-order derivatives

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- Use Taylor series

$$f(x_{j-1}) = f(x_j) - hf'(x_j) + \frac{h^2 f''(x_j)}{2} - \frac{h^3 f'''(x_j)}{6} + \dots$$

$$f(x_{j+1}) = f(x_j) + hf'(x_j) + \frac{h^2 f''(x_j)}{2} + \frac{h^3 f'''(x_j)}{6} + \dots$$

$$f(x_{j-1}) + f(x_{j+1}) = 2f(x_j) + h^2 f''(x_j) + \frac{h^4 f''''(x_j)}{24} + \dots,$$

$$f''(x_j) \approx \frac{f(x_{j+1}) - 2f(x_j) + f(x_{j-1}))}{h^2}$$



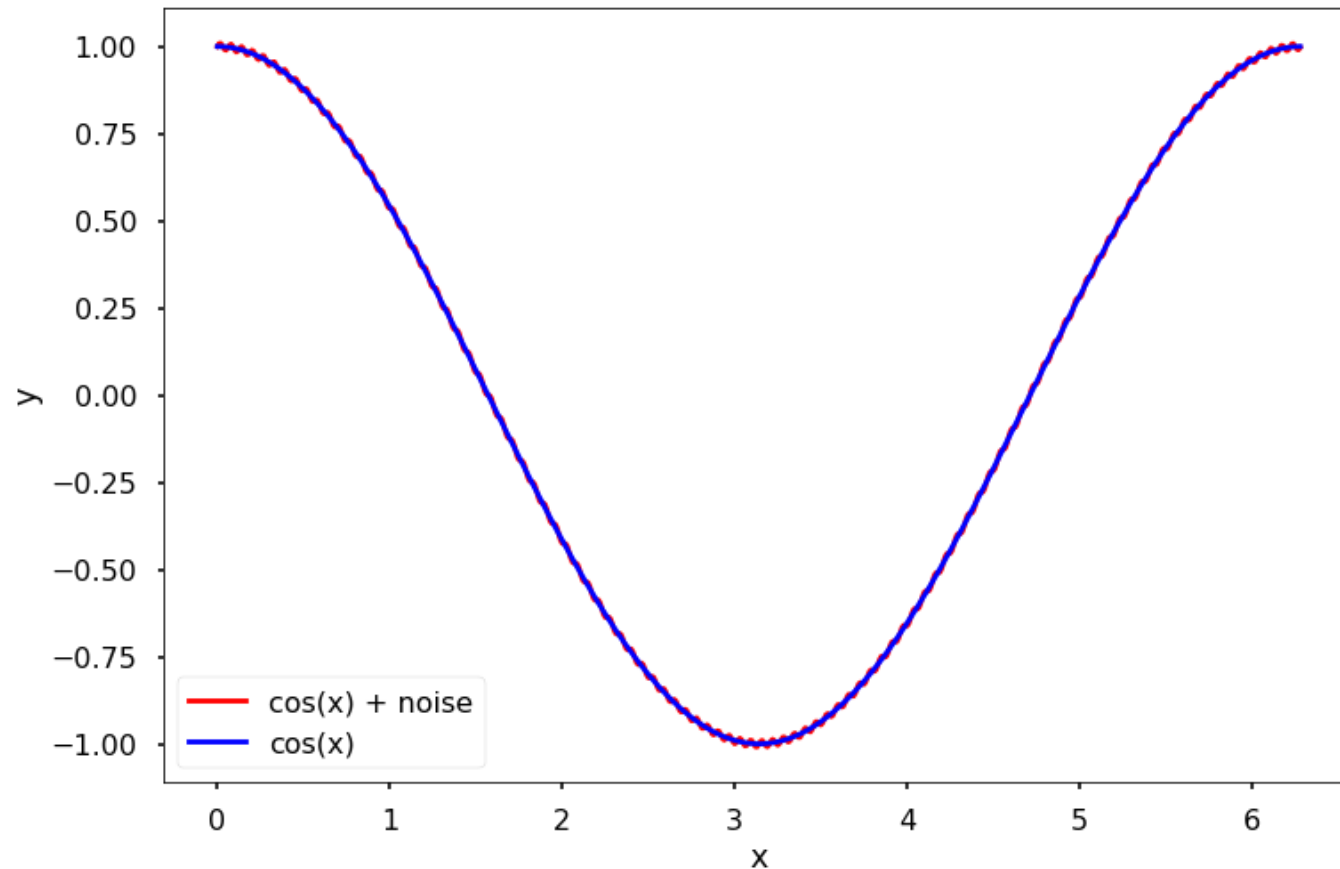
# Sensitivity w.r.t. noise

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- Sometimes data are contaminated with noise, i.e.,  
data = theoretical value + random offset
- Differentiation is sensitive to noise
  - Even if noise is small, its derivative may be significant
- Consider  $f(x) = \cos(x)$ , and  $f_{\text{noise}} = \cos(x) + e \cdot \sin(wx)$ ,  
where  $e = 0.01$  and  $w = 100$ .

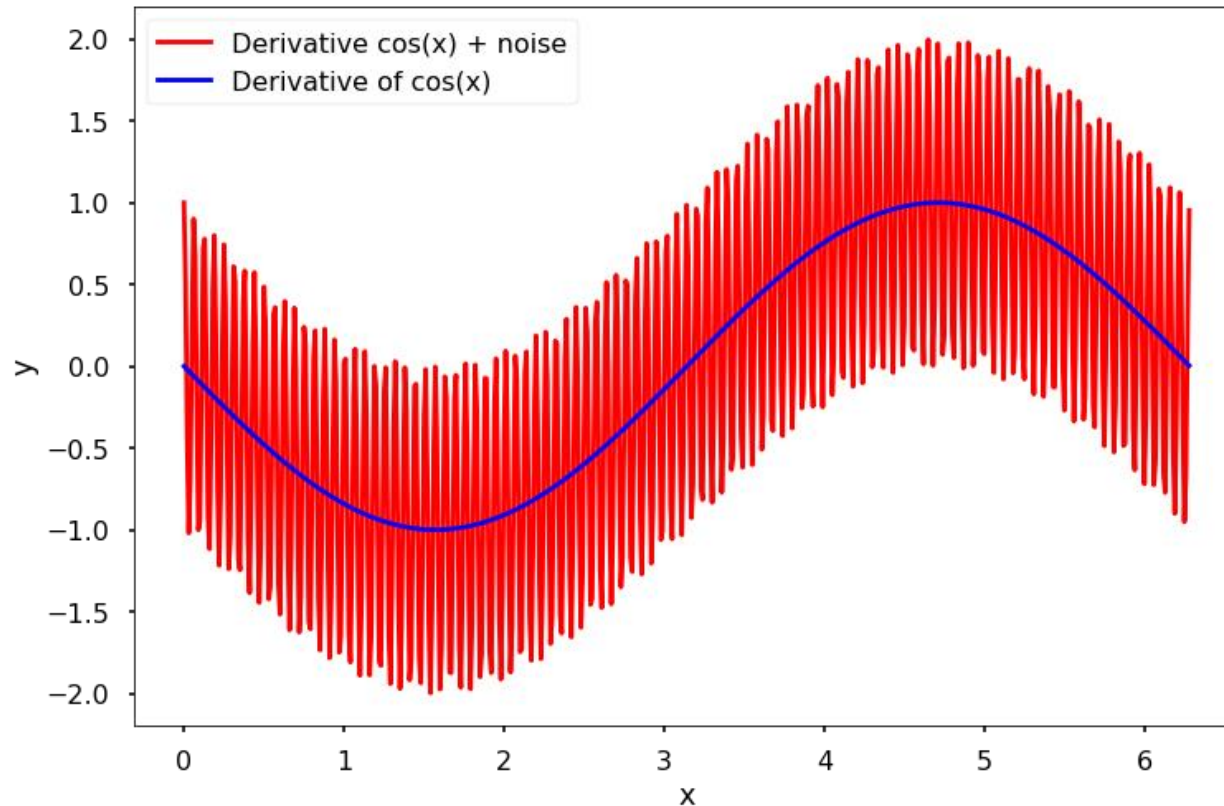
# Plot of $f$ vs. $f_{\text{noise}}$

Can you write code to compare  $f$  and  $f_{\text{noise}}$  in a figure?



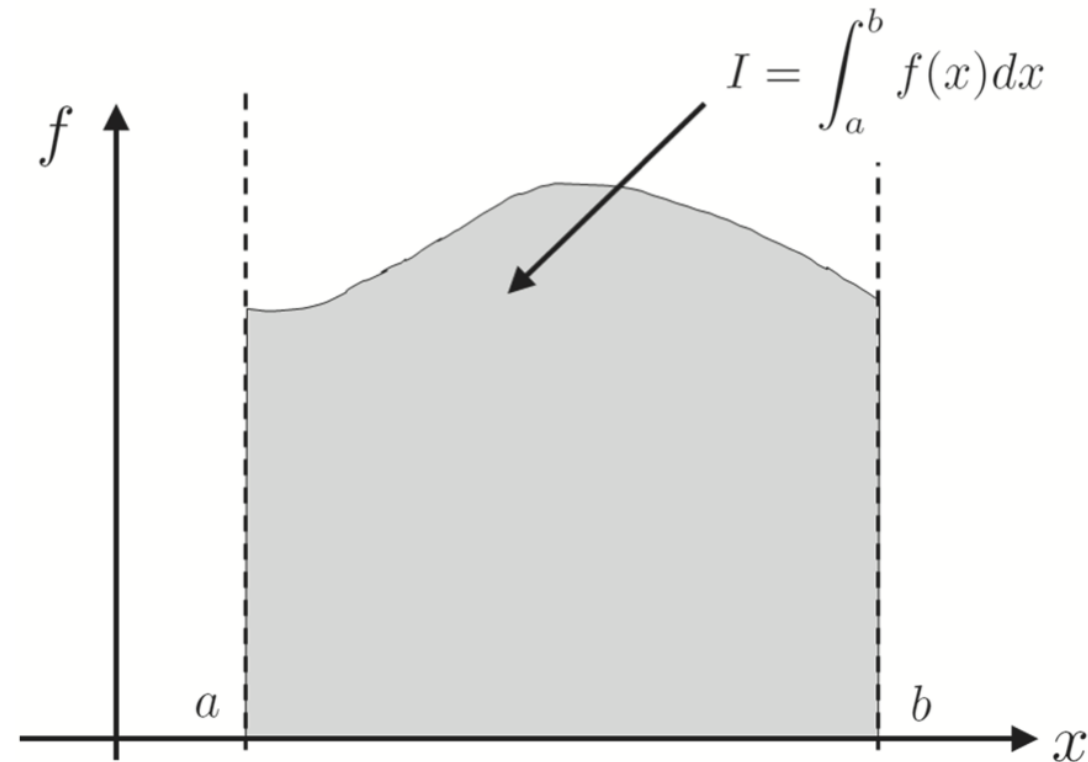
# Compare $f'$ and $f'_{\text{noise}}$

- Can you write code to compare their derivatives?



# Numerical Integration

- Compute the integral of  $f(x)$  given  $f(x)$
- Such an integral typically described as *area under the curve*.
- Many applications in modeling, predicting, and understanding of physics.



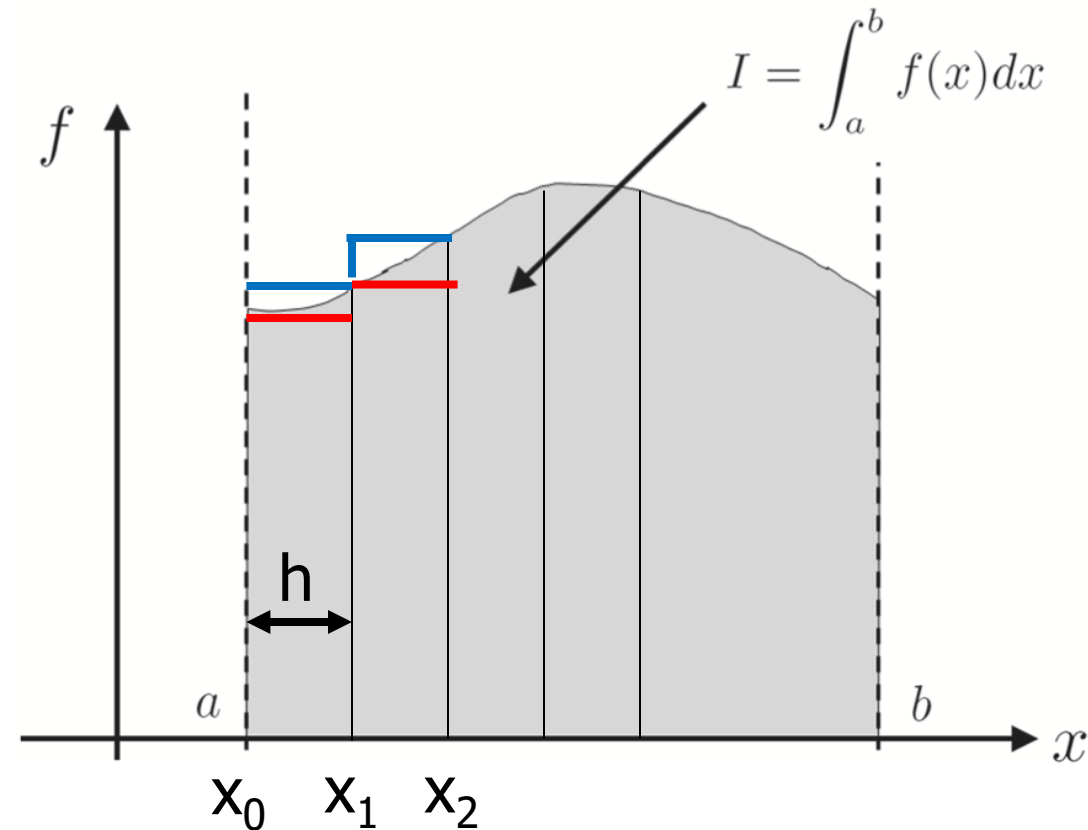


# Typical process to approximate integral

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- Discretize the interval  $[a,b]$  into a numerical grid, consisting of  $n+1$  points with spacing  $h = (b-a)/n$ .
- Let  $x_i$  be the corresponding  $i$ th grid points ( $x_0=a$ ,  $x_n=b$ ).
- We can compute  $f(x_i)$ ,  $i=0,\dots,n$ .
- The integral is typically approximated as the sum of the areas for each subinterval  $[x_i, x_{i+1})$ .

# Riemanns integral



- Summing the area of *rectangles*

- Left

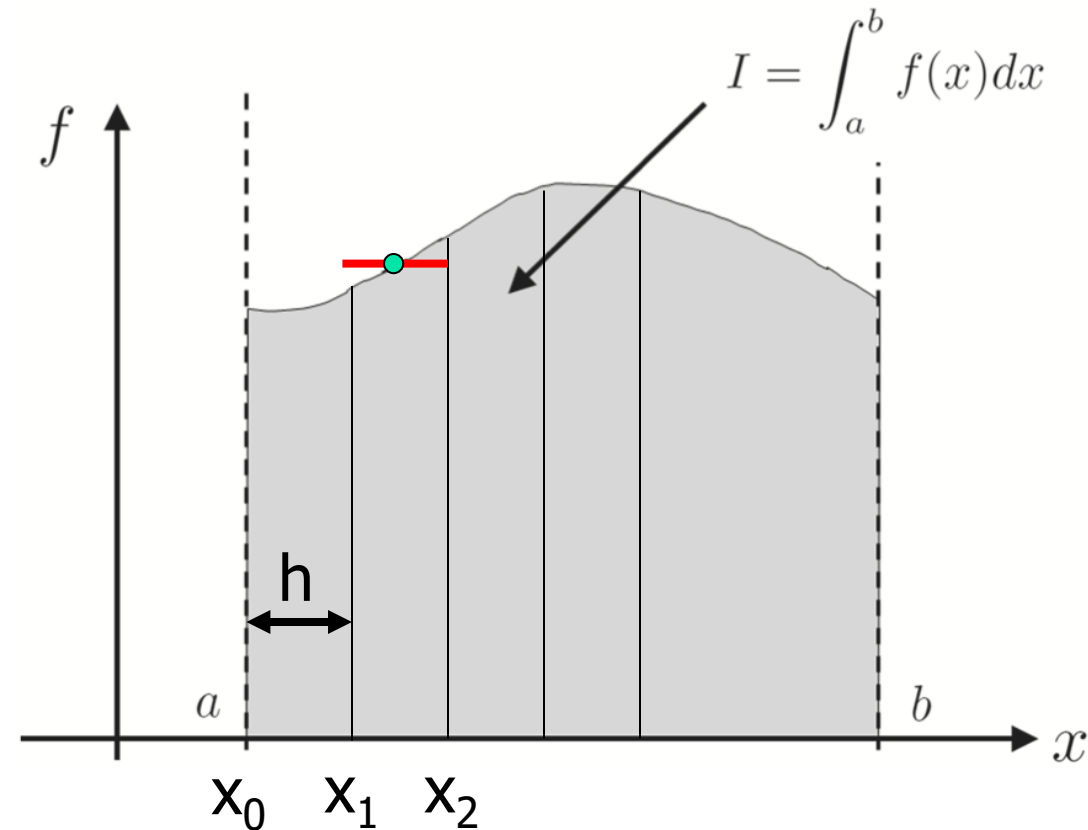
- $$\int_a^b f(x) dx \approx \sum_{i=0}^{n-1} h f(x_i),$$

- Right

- $$\int_a^b f(x) dx \approx \sum_{i=1}^n h f(x_i),$$

- Overall accuracy:  $O(h)$

# Midpoint rule



$$\int_a^b f(x) dx \approx \sum_{i=0}^{n-1} h f\left(\frac{x_i + x_{i+1}}{2}\right).$$

- Overall accuracy:  $O(h^2)$ , better than the previous two methods
- If  $f(x)$  is given as data points, we can't use this rule.



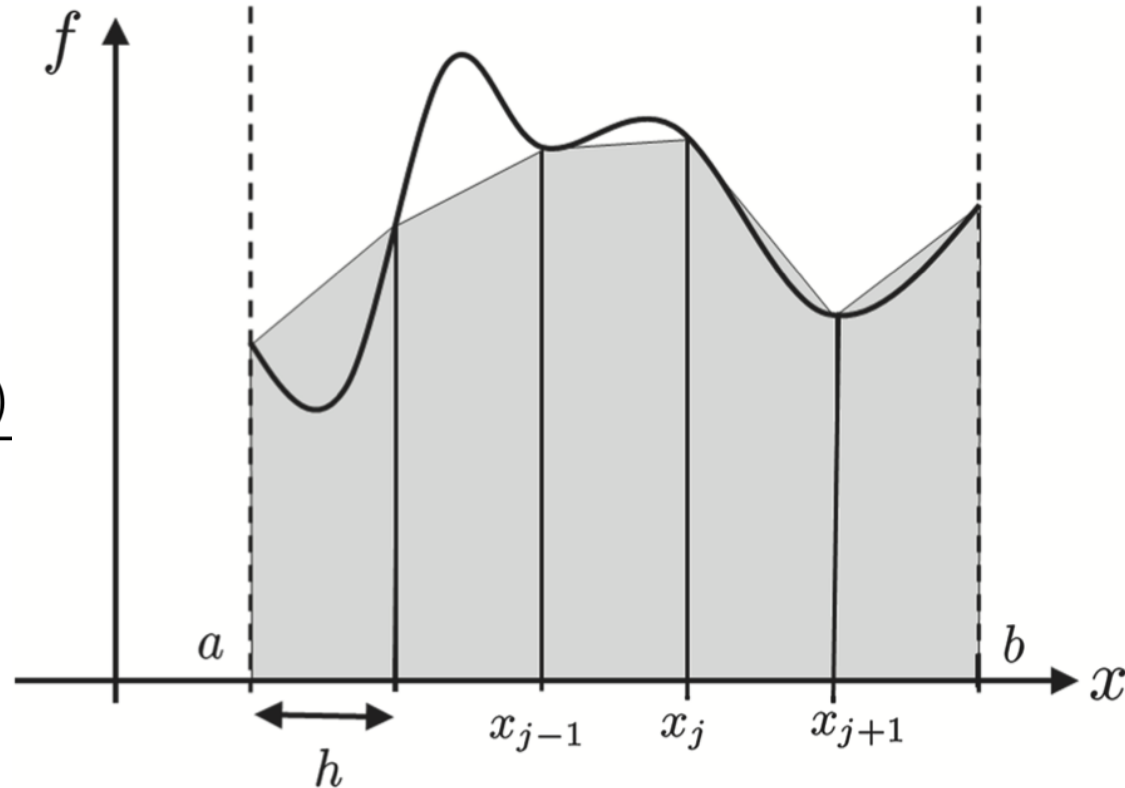
# Trapezoid Rule

- Fits a trapezoid into each subinterval and sums the areas of the trapezoids.

$$\int_a^b f(x) dx \approx \sum_{i=0}^{n-1} h \frac{f(x_i) + f(x_{i+1})}{2}$$

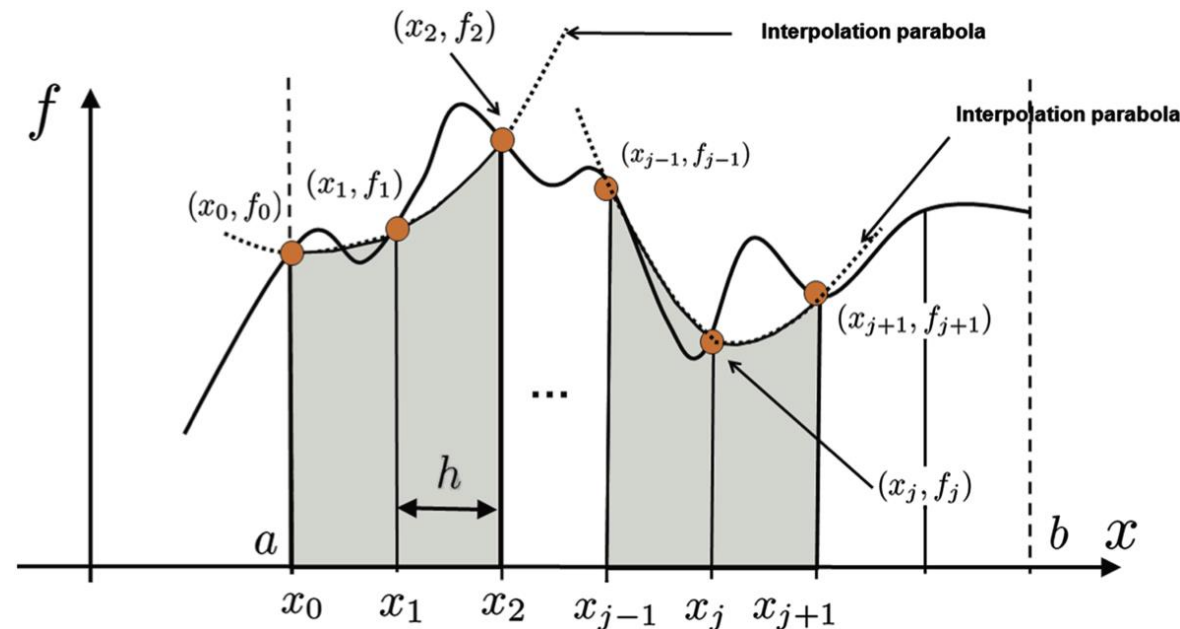
- Overall accuracy:  $O(h^2)$
- Simplified form:

$$\int_a^b f(x) dx \approx \frac{h}{2} \left( f(x_0) + 2 \left( \sum_{i=1}^{n-1} f(x_i) \right) + f(x_n) \right)$$



# Simpson's Rule

- Approximates the area under  $f(x)$  over two consecutive subintervals by fitting a quadratic polynomial through  $(x_{i-1}, f(x_{i-1}))$ ,  $(x_i, f(x_i))$ ,  $(x_{i+1}, f(x_{i+1}))$

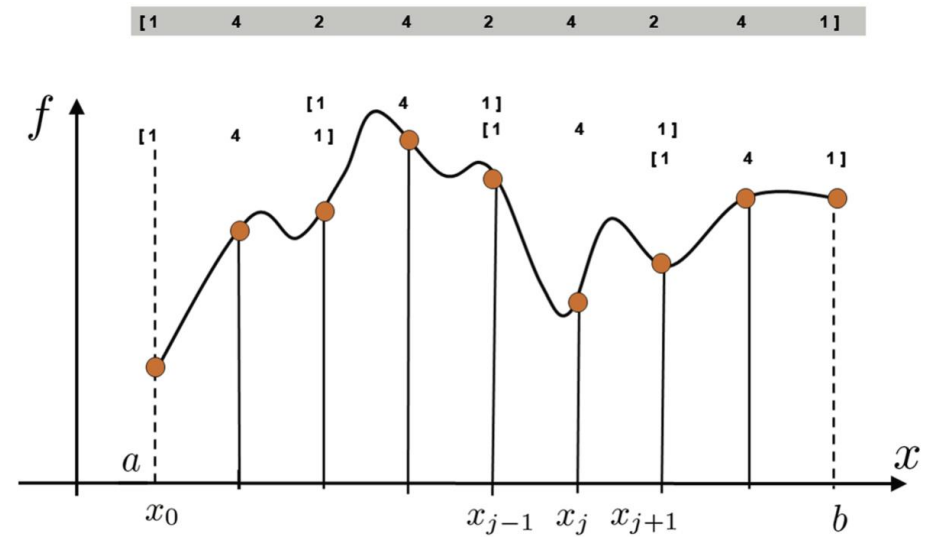


# Formula

- Must have an even number of intervals (i.e., an odd number of grid points)

$$\int_a^b f(x)dx \approx \frac{h}{3} \left[ f(x_0) + 4 \left( \sum_{i=1, i \text{ odd}}^{n-1} f(x_i) \right) + 2 \left( \sum_{i=2, i \text{ even}}^{n-2} f(x_i) \right) + f(x_n) \right].$$

- Overall accuracy:  $O(h^4)$





# Example

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- Use the left Riemann Integral, right Riemann Integral, Midpoint Rule, Trapezoid Rule, Simpson's Rule to approximate the integration of  $\sin(x)$  from 0 to  $\pi$  with 11 evenly spaced grid points over the whole interval. Compare this value to the exact value of 2.



# Python implementations

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- The `scipy.integrate` submodule has several functions related to integrals
- `trapez` takes an array of function values of  $f$  on a numerical grid and computes the integral using trapezoid rule

```
import numpy as np
from scipy.integrate import trapz
a = 0
b = np.pi
n = 11
h = (b - a) / (n - 1)
x = np.linspace(a, b, n)
f = np.sin(x)
I_trapz = trapz(f,x)
I_trap = (h/2)*(f[0] + 2 * sum(f[1:n-1]) +
f[n-1])
print(I_trapz)
print(I_trap)
```



# The quad function

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- `quad(f, a, b)`: use different numerical techniques to integrate by function object `f` from `a` to `b`

```
from scipy.integrate import quad
I_quad, est_err_quad = \
    quad(np.sin, 0, np.pi)
print(I_quad)
err_quad = 2 - I_quad
print(est_err_quad, err_quad)
```