



# Generic formulation of BVP

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$$F \left( x, f(x), \frac{df(x)}{dx}, \frac{d^2 f(x)}{dx^2}, \frac{d^3 f(x)}{dx^3}, \dots, \frac{d^{n-1} f(x)}{dx^{n-1}} \right) = \frac{d^n f(x)}{dx^n},$$

- $x$  in a region  $[a,b]$ , we need  $n$  boundary conditions at value  $a$  and  $b$ .
- For 2<sup>nd</sup> order case, we have different cases
  - $f(a)$  and  $f(b)$  are given
  - $f'(a)$  and  $f'(b)$  are given
  - $f(a)$  and  $f'(b)$  are given or  $f(b)$  and  $f'(a)$  are given

Two-point BVP



# Python BVP solver

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- `scipy.integrate.solve_bvp`

**`solve_bvp(fun, bc, x, y, p=None, S=None, fun_jac=None, bc_jac=None, tol=0.001, max_nodes=1000, verbose=0, bc_tol=None)`**

- `fun`: similar to `ivp`, `fun(x,y)` or `fun(x,y,p)`
- `bc`: boundary conditions
- `x`: initial mesh
- `y`: initial guess at the mesh nodes

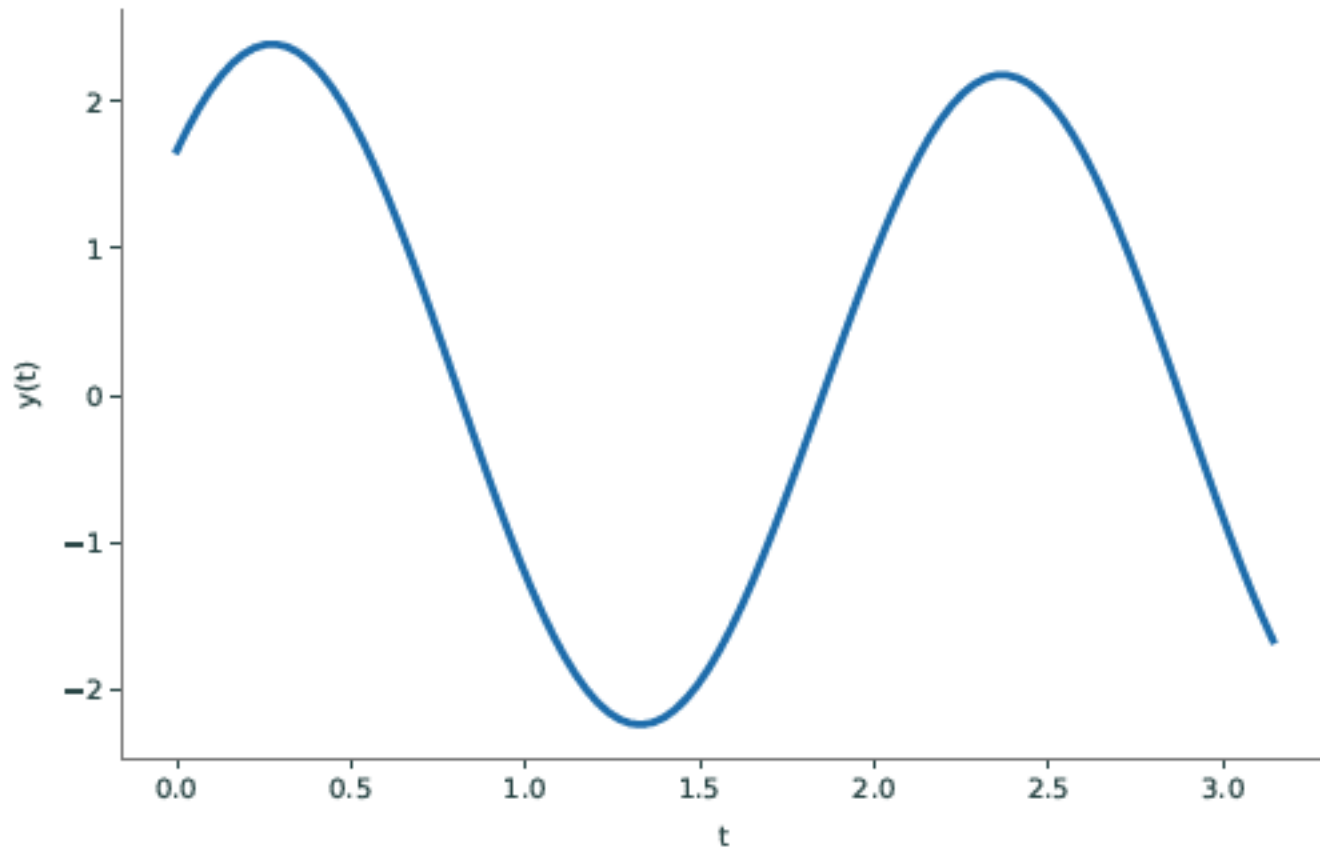
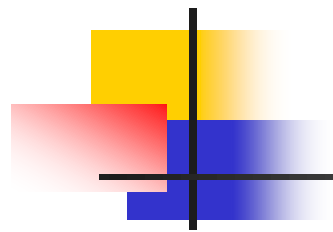


## Example

$$y'' + 9y = \cos(t), \quad y'(0) = 5, \quad y(\pi) = -5/3$$
$$S = [y, y'], \quad S' = [y', y'']$$

```
from scipy.integrate import solve_bvp
import numpy as np
# element 1: the ODE function
def ode(t,S):
    """ define the ode system """
    return [S[1], np.cos(t) - 9*S[0]]
# element 2: the boundary condition function
def bc(ya,yb):
    """ define the boundary conditions """
    # ya are the initial values, value of S at t0
    # yb are the final values, i.e., value of S at tf
    # the returned array will be set to zero
    return np.array([ya[1] - 5, yb[0] + 5/3])
```

```
# element 3: the time domain.
t_steps = 100
t = np.linspace(0,np.pi,t_steps)
# element 4: the initial guess.
y0 = np.ones((2,t_steps))
# Solve the system.
sol = solve_bvp(ode, bc, t, y0)
import matplotlib.pyplot as plt
# here we plot sol.x instead of sol.t
plt.plot(sol.x, sol.y[0])
plt.xlabel('t')
plt.ylabel('y(t)')
plt.show()
```



- fun remains the same as ivp problem
- Must provide bc: 2 arrays representing initial and final values. bc evaluate to zero.
- Pass a linspace of  $[t_0, t_f]$
- Pass an initial guess for all values



# Notes

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- `sol.sol` is a callable function. Plug in any value or numpy array, e.g., `sol.sol(np.linspace)`, `sol.sol(float)`, `sol.sol(list)`.
- Pay attention to the initial values. Small changes can lead to large difference in the final approximations.
- BVP with free parameters can also be addressed.

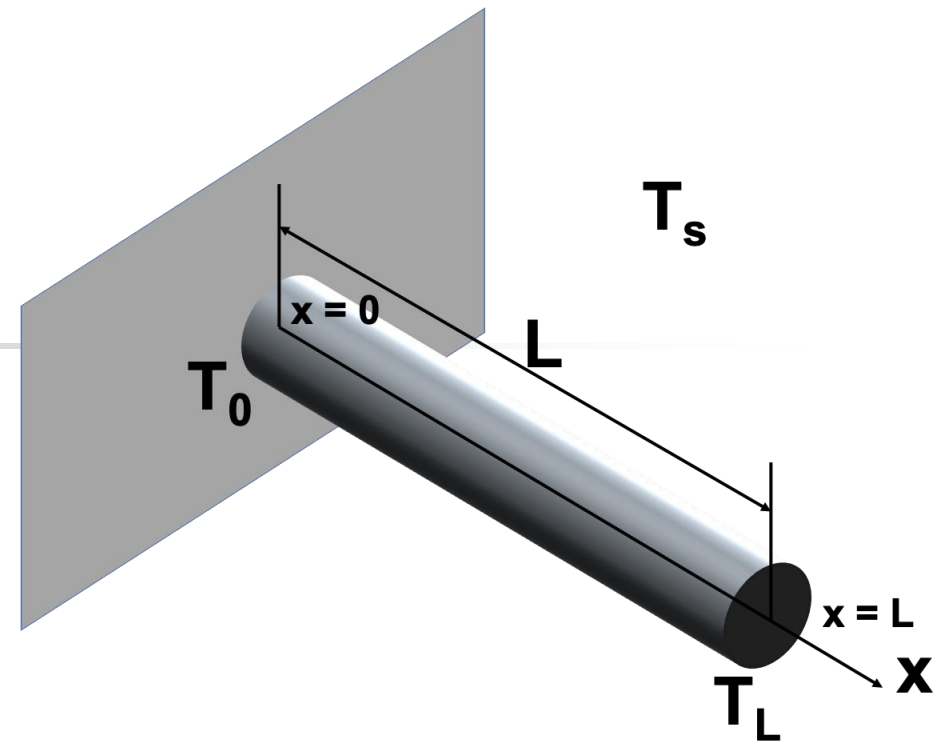
# Example: cooling pin fin

- Steady state temperature distribution  $T(x)$

$$\frac{d^2 T}{dx^2} - \alpha_1 (T - T_s) - \alpha_2 (T^4 - T_s^4) = 0$$

$$\alpha_1 = \frac{h_c P}{k A_c} \quad \alpha_2 = \frac{\epsilon \sigma_{SB} P}{k A_c}$$

- $L = 0.2$  m
- $T(0) = T_0 = 475$  K
- $T(0.1) = 290$  K
- $T_s = 290$  K
- Determine  $T(x)$



$h_c = 40$  W/m<sup>2</sup>/K

Convective heat transfer coefficient

$P = 0.015$  m

Perimeter bounding the cross section

$K = 240$  W/m/K

Thermal conductivity

$A_c = 1.55 \times 10^{-5}$  m<sup>2</sup>

Cross section area

$\epsilon = 0.4$

Radiative emissivity

$\sigma_{SB} = 5.67 \times 10^{-8}$  W / (m<sup>2</sup>K<sup>2</sup>)

Stefan-Boltzmann constant